1	The influence of performing gesture type on interpersonal
2	musical timing, and the role of visual contact and tempo
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5	
6	Abstract
7	Bodily gestures play an important role in the communication of expressive intentions
8	between humans. Music ensemble performance, as an outstanding example of nonverbal
9	human communication, offers an exemplary context to study and understand the gestural
10	control and communication of these expressive intentions. An important mechanism in music
11	ensemble performance is the anticipation and control of interpersonal timing. When
12	performing, musicians are involved in a complex system of mutual adaptation which is not
13	completely understood so far. In this study, we investigated the role of performers' gestures
14	in the mediation process of interpersonal timing in a dyad performance. Therefore, we
15	designed an experiment in which we controlled for the use of hand and arm movements in a
16	musical task, in which dyads were asked to synchronously tap out a melody. Next to their
17	comfortable/natural way of tapping, we instructed participants to either perform pronounced
18	expressive hand and arm gestures in between successive taps, or to restrict from any overt
19	body movement. In addition, we looked at effects of visual contact (yes/no) and tempo (slow:
20	50 beats per minute; fast: 100 beats per minute). The results show that performers' gestures
21	improve interpersonal musical timing, in terms of the consistency and accuracy of onset
22	asynchronies, and of the variability of produced inter-onset intervals. Interestingly, we found
23	that the use of expressive gestures, in regard to comfortable/natural movements, add to these
24	positive timing effects, but only when there is visual contact and at the slow tempo. In
25	addition, we found that the type of gestures employed by musicians may modulate leader-
26	follower dynamics. Together, these findings are explained by human anticipation
27	mechanisms facilitated by gesturing, shedding new light on the principles underlying human
28	communication of expressive intentions, through music.
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36	The role of performers' gestures in joint musical communication
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38	Music provides a powerful medium for humans to communicate, to share and explore
39	emotions, and to create a deep sense of mutual understanding and togetherness (Lesaffre,
40	Maes, & Leman, 2017; Miell, MacDonald, & Hargreaves, 2005). Most forms of musical
41	communication involve direct gestural interaction, where the flow of multi-sensory
42	information mediated by corporeal articulations enables expressive interactions (Leman,
43	2016). Performing music together however is a highly complex task, as it requires fine-tuned
44	motor coordination and high-level cognitive skills. It is truly remarkable how music
45	performers (and their audiences) manage to organize their behavior into strongly coupled
46	activity (cf. entrainment) to create experiences of shared sense-making and feeling. From a
47	scientific point of view, a key challenge is to better understand the fundamental mechanisms
48	underlying the human ability to keep track of time, to produce regular temporal intervals,
49	and to align to the timing of co-performers' actions.
50	
51	Different approaches have been proposed to account for motor control mechanisms

52 underlying (quasi-)periodic interval production. This research points out that these 53 mechanisms are to a large degree task- and context-dependent. One of the determining factors is the availability of sensorimotor information, related to self-produced actions and to sensory 54 55 information received from the external environment. Previous research puts forth that the 56 execution of continuous bodily movements may underlie an emergent time-keeping 57 mechanism (Cassenti, 2011; Delignières, Lemoine, & Torre, 2004; Maes, Wanderley, & Palmer, 2015; Robertson et al., 1999; Torre & Balasubramaniam, 2009). In this view, timing 58 59 emerges from the control of movement dynamics, rather than being explicitly controlled by a dedicated internal clock. In addition, humans have been shown to be highly receptive to time-60 61 varying sensory patterns, which may equally support time-keeping and synchronization 62 (Coull & Droit-Volet, 2018; Maes, Giacofci, & Leman, 2015; Motanis, Seay, & Buonomano, 63 2018; Schwartze, Tavano, Schröger, & Kotz, 2012). In short, spatiotemporal patterns emerging from human sensorimotor interactions with the world may provide important 64 information about the dynamical properties in the performance of musical ensembles. 65 However, at instances where one cannot rely on bodily gestures and/or sensory information, 66 67 internal neural mechanisms are expected to be deployed instead for keeping track of time. At

68 current, there is a general agreement that there is no single, dedicated internal "clock" 69 residing within the brain, but that time is encoded in dynamical patterns of neural activity 70 within a distributed network, including cortical areas, basal ganglia, and cerebellum (Allman, 71 Teki, Griffiths, & Meck, 2014; Buhusi & Meck, 2005; Karmarkar & Buonomano, 2007; 72 Kononowicz, van Rijn, & Meck, 2016; Remington, Egger, Narain, Wang, & Jazayeri, 2018). 73 Based on this theoretical framework, it is to be expected that bodily movements and 74 available sensory information play a functional role in musical timing. Indeed, previous 75 research has indicated that continuous body movements and auditory (tone) feedback may 76 support (individual) timing production in musical tasks, in particular in conditions of 77 heightened cognitive load (Maes, Giacofci, et al., 2015; Maes, Wanderley, et al., 2015). In 78 the context of music ensemble coordination, it has been shown that head nods, body swaying 79 and gaze patterns play an important role in establishing and maintaining interpersonal 80 synchrony and leader-follower relations (Keller, 2014). Here, body movements associated 81 with music performance can provide visual cues, which in combination with the timing cues 82 from the auditory domain regulate the coordination and communication between ensemble 83 performers. Keller and Appel (2010) for instance found that the coordination of body sway 84 was related with the synchronization between participants. According to Goebl and Palmer 85 (2009), pianists' head movements became more synchronized when auditory feedback was 86 reduced in the performance. They also noticed that pianists who were designated as the leader 87 raised their fingers higher and preceded the other pianist in timing. This research suggests 88 that bodily gestures can help in communicating and controlling timing in ensemble 89 performance. This is parallel to language communication, where hand gestures have been 90 shown to convey (semantic) information and foster mutual understanding (Krauss, Chen, & 91 Chawla, 1996).

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93 However, most research on ensemble coordination consist of manipulating the 94 conditions in which sensory exchange is possible and/or manipulating the leader-follower roles, but not the bodily movements themselves. This is likely due to the fact that sensory 95 96 conditions and leader-follower roles can be more easily manipulated. More critical is to 97 manipulate the performers' body movements, as these make out a functional aspect of a 98 musical performance. Yet research indicates that, though each musician has his/her own typical movement repertoire and peculiarities, musicians may vary gestural patterns 99 100 according to differences in performance style (Caruso, Coorevits, Nijs, & Leman, 2016;

101 Davidson, 2012; Demos, Chaffin, & Logan, 2018; Teixeira, Loureiro, Wanderley, & Yehia,

102 2015) (Davidson, 2012; Teixeira, Loureiro, Wanderley, & Yehia, 2015). In addition, experimental control of body movements in playing a musical piece has been applied 103 104 previously, in particular to investigate effects on the perception of expressive and emotional intentions (Dahl & Friberg, 2004; Davidson, 1993; Juchniewicz, 2008) (Davidson, 1993; 105 Dahl & Friberg, 2003; Juchniewicz, 2008). This raises the question how deliberately 106 107 manipulating bodily gestures might affect the entrainment dynamics of ensemble 108 performance in terms of timing control, synchronization, and leader-follower relationships. For that purpose, we conceived of a simple musical task, namely two musicians tapping a 109 110 beat together. Tapping a beat together can be considered as the necessary basis of coupled 111 musical interactions, on top of which more elaborated musical structures and expressive 112 nuances can be build. Therefore, it is of interest to study deeper how gestures may regulate 113 this basic coupling behavior. We controlled thereby for the use of hand and arm movements; 114 next to their comfortable/natural way of tapping, we instructed participants to either perform 115 pronounced (but naturally feeling) expressive hand and arm gestures in between successive taps, or to restrict from any overt body movement. We expected that the onset asynchronies 116 117 between performers would be smaller when they perform expressive movements in between the taps, and vice versa, be larger when no movement in between onsets is allowed. We 118 119 hypothesized that expressive gestures will contribute to interpersonal timing, as these 120 gestures have time-varying properties that can support the communication of intentions. In 121 addition, we are interested in studying how expressive gestures may modulate leader-follower dynamics in a dyad's interaction. As expressive gestures may contain temporal information, it 122 123 was expected that the participant who was attributed the expressive (continuous) gesture type, 124 could communicate timing information more effectively, and in turn, would be inclined 125 taking the leader role with respect to the participant who could not perform movements (and communicate timing information) in between tone onsets. The direction of asynchronies 126 127 would then show who anticipates whom in terms of timing. We expect that gestures will help 128 to convey musical time and anticipate the expressive timing patterns of a co-performer. 129 130 Further, we wanted to assess the roles of two additional factors, namely visual exchange of information and tempo, as these were expected to modulate the effects of 131 132 hand/arm movement manipulations. Concerning the exchange of visual information, previous research has shown that the 133 observation of performers' gestural behavior may contribute to listeners' perception of 134 musical parameters, such as pitch (Thompson, Russo, & Livingstone, 2010) and tone duration 135

136 (Schutz & Lipscomb, 2007). Also, studies have demonstrated that gestural information may

137 affect the perception of musical expressiveness and emotion (Dahl & Friberg, 2007;

138 Davidson, 1993, 2012; Krahé, Hahn, & Whitney, 2015; Thompson, Graham, & Russo, 2005;

139 Vines, Krumhansl, Wanderley, Dalca, & Levitin, 2011; Vuoskoski, Thompson, Clarke, &

140 Spence, 2014) and may substantially influence an audience's appreciation and evaluation of a

141 music performance (Nusseck & Wanderley, 2009; Platz & Kopiez, 2012; Tsay, 2013, 2014).

142 Interestingly, also in the context of ensemble music performance, research have indicated that

143 gestures may be useful in signaling musical intentions (both on an expressive-emotional and

144 music-structural level), and hence support joint musical coordination. In particular, gestures

145 have been proven useful when auditory information or feedback is not reliable, ambiguous or

146 absent (Bishop & Goebl, 2015; Demos, Carter, Wanderley, & Palmer, 2017; Goebl &

147 Palmer, 2009). In these cases, gestures, and their visual exchange, may have a compensatory

148 role in support of a reliable exchange of musical intentions. Based on this earlier research, we

149 hypothesized in the present study that effects of movement type on interpersonal timing will

150 be more pronounced in a performance context where musicians can visually communicate,

151 compared to when musicians' cannot see each other's movements. Taking into account this

152 factor is of particular interest as it allowed to dissociate between effects of movement

153 execution and of the visual exchange of gestural information.

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155 In addition, we investigated effects of the tempo at which musical tones needed to be produced (slow: 50 beats per minute, inter-onset interval (IOI)=1200 ms; fast: 100 beats per 156 157 minute, IOI=600 ms). Previous research has indicated that there are differences in the 158 mechanisms underlying the production of supra-second and sub-second temporal intervals. 159 Early accounts pointed towards largely independent brain mechanisms; cognitively-controlled 160 timing mechanisms – involving prefrontal and parietal cortical functions – for supra-second interval production, and *automatic* timing mechanisms – involving the motor system and 161 162 cerebellum - for sub-second interval mechanisms (Lewis & Miall, 2003, 2006). However, 163 more recent accounts have argued for a more nuanced and unified view by pointing out a 164 timing mechanism common to both sub-second and supra-second temporal intervals, based on differentiated interactions within a distributed cerebellar-thalamic-striatal-cortical neural 165 166 network (Koch, Oliveri, & Caltagirone, 2009; Petter, Lusk, Hesslow, & Meck, 2016). In line 167 with this research, it is to be expected that the production of longer (supra-second) intervals 168 relies more on an explicit and conscious representation of these intervals, while the 169 production of shorter (sub-second) intervals relies more on implicit and automatic timing

170	mechanisms. Hence, it is to be expected that the use of continuous expressive gestures may
171	be most beneficial for interpersonal timing at slower tempi, as there is first of all more time to
172	encode temporal cues within the performed gestures and second of all, as the perceived
173	temporal cues can be processed more explicitly and consciously.
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175	To summarize, the following research questions were investigated in the present
176	study. (i) The central research question was whether the type of performed (hand and arm)
177	movements (baseline/expressive gesture/no movement) had an effect on interpersonal timing,
178	synchronization and leader-follower relationships. We expected that the ability to make
179	expressive gestures would contribute positively to timing and synchronization, and would
180	stimulate performers to take the leader role. (ii) In addition, we wanted to investigate whether
181	the visual observation of gestures (yes/no), and tempo (slow/fast) are factors that could
182	further modulate the effects of hand/arm movement manipulations. We expected that the
183	positive effects of expressive gestures on the performance measures would be more
184	pronounced when visual observation is possible, and at the slower tempo. In the following,
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184 185 186 187 188 189 190 191 192 193 194 195	pronounced when visual observation is possible, and at the slower tempo. In the following, we will present in detail the experiment that was conducted to test these hypotheses. Method Participants The study was approved by the Ethical Committee of the Faculty of Arts and Literature of Ghent University, Belgium. Participants' written informed consent was obtained prior to participation. In total, 14 dyads (28 participants) of musically trained people with at least six years of formal musical training and ensemble experience were tested. Two dyads were removed from further analysis due to technical problems during the recordings. The remaining participants were between 18 and 50 years old (M= 28), 12 of them were female, 12 of them

198 Materials

199 We provided each participant with a single tapping pad, by means of which they

200 could trigger tones, audible through headphones. Successive taps on a pad triggered the

201 successive notes of a melody, so there was a one-to-one relationship of taps to note onsets.

202 The melody they produced was an excerpt from the Pachelbel Canon, plus a final note to end

203 the sequence (see Fig. 1). All bars contained four quarter notes, meaning that for each trial,

205 voice (one got the upper voice, the other one the lower voice). As the two voices in this 206 canon are of equal importance and have an equal note rate, no hierarchy of leader or follower 207 was induced. To distinguish between the tones produced by their own taps and those of their 208 co-performer, left-right panning of the voices was applied. The taps of the participants were 209 recorded with a strain gauge-based pressure sensor under a tapping pad (in a Wheatstone bridge configuration), at a sample rate of 1000 Hz. These sensors were able to measure 210 deformation of material caused by taps and quickly translate this deformation into voltage 211 212 changes (amplifier' chip type INA 125). Once the voltage exceeded a predefined threshold, then a 'drum-hit' was recognized by an Axoloti device (a low-latency micro-controller 213 suitable for digital audio production, http://www.axoloti.com/). The Axoloti then quickly 214 reacted by providing a sound; that is, the next note in the musical stimulus (see Fig. I) to a 215 participant. 216

both participants produced 33 tones (with the final tone included). Each participant got one

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Figure 1. Musical excerpt used for the experiment. One participant triggers the notes of the
upper voice, the other one the notes of the lower voice.

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222 Design

223 The goal of the experiment was to investigate the role of three factors in interpersonal timing within the dyads' performances. The first factor is Movement type. Individuals were 224 instructed to tap (i) in a way they would do spontaneously without any further instruction, so 225 they didn't had to think about "how to tap" (baseline; comfortable/natural), (ii) with an 226 227 additional expressive gesture of the (dominant) arm and hand in between taps, which resulted 228 in a continuous movement trajectory between the taps (expressive gesture), or (iii) using the 229 least movement possible by pushing on the tapping pad without lifting the finger (no 230 movement). This leads to five combinations of performance strategies (P1(i)-P2(i), P1(ii)-P2(ii), P1(ii)-P2(iii), P1(iii)-P2(ii), P1(iii)-P2(iii))). Note that the baseline Movement type 231 232 was not combined with the other movement strategies. These conditions were randomized between the participating dyads, though the combined baseline Movement type was always 233

the first one (see Fig. 2). The second factor was Visual contact. In one part of the experiment,

- participants could see each other's arms and hands, but not each other's faces (visual
- contact), while in the other part they could not see each other, at all (no visual contact). A
- third factor was Tempo. All the combinations of Movement type and Visual contact were
- repeated in a fast (100 beats per minute, bpm, IOI = 600 ms) and a slow tempo (50 bpm,
- 239 IOI=1200 ms). In total, this sums up to $2 \times 2 \times 5$ conditions. In each condition, participants
- 240 performed three trials, making 60 trials in total.
- 241

242 Procedure and task

243 Before coming to the lab, participants were screened on musical background and 244 dominant hand. On arriving, they got clear instructions about the experiment, and signed an 245 informed consent form. Before starting the actual experiment, participants received enough time to learn how to trigger the melody on the tapping pad in the different performing 246 247 strategies (see above (i), (ii), (iii)) and in the different tempi. Next, the actual experiment 248 started. Each trial was initiated with a metronome that indicated the tempo with two bars of 249 four beats. After these two bars, the metronome stopped and the participants started tapping. The main instruction they received beforehand was to play together as good as possible while 250 251 performing the Pachelbel Canon, within the tempo indicated by the metronome at the beginning of the trial (in order to avoid that participants would deliberately speed up or slow 252 253 down throughout a trial). As indicated in Fig. 2, half of the dyads started with the condition where they could see each other's movements, the other half started without visual contact. 254 255 When all the conditions and trials in one modality were performed, the experiment was 256 repeated in the other modality and in the two different tempi, which were also randomized. 257 After the participants had gone through the whole procedure, they had to fill out a questionnaire in which they were asked about their experiences during the experiment and 258 259 their opinion about the task. It took approximately 2.5 hours to complete the whole 260 experiment. Afterwards, all participants received a cd-voucher with which they could buy CDs for an amount of $\in 15$. 261

	Visual contact	No visual contact
	Slow	w
263	Figure 2. Schematic representation of the experiment	al design, and the ordering of the
264	different factors involved: Movement type (i-i, ii-ii, ii-iii,	iii-ii), Tempo (slow/fast), and
265	5 Visual contact (yes/no). Arrows indicate r	andomizations.
266	-	
200	7	
207	Dependent variables	
200		
209	Internersonal synchronization (consistency D and	Lagunahuany Φ) International
270	interpersonal synchronization (consistency K, and	asynchrony Ψ). Interpersonal
2/1	synchronization of dyads was assessed by looking at the pha	se relationship of tapping onsets
272	2 throughout time. The phase of each tap of participant 2 (low	er voice) relative to the closest
273	3 tap of participant 1 (upper voice) was expressed as an angle	between -180° and $+180^{\circ}$; with
274	0° meaning that the onset of participant 2 occurred simultane	eously with the onset of
275	5 participant 1, a negative angle meaning that the onset of part	icipant 2 anticipated the onset of
276	5 participant 1, and a positive angle meaning that the onset of	participant 2 delayed the onset of
277	7 participant 1. Hence, for each performance, a distribution of	33 phase angles was obtained,
278	3 which represented the relative phase differences between all	corresponding onsets of the
279	9 dyad. By calculating the average of the sine and cosine coord	linates of all phase angles, we
280	obtained the mean resultant vector, which has a specific leng	th R and angle Φ (Fisher, 1995).
281	The resultant vector length R is related to the (circula	ar) variance of phase angles and
282	2 ranges from 0 to 1; with 0 meaning that phase angles are ran	domly distributed between -180°
283	and $+180^{\circ}$, and 1 meaning that there is a constant relative ph	ase between a dyad's onsets.
284	Therefore, resultant vector length R is taken as measure for a	a dyad's synchronization
285	5 consistency ($0 = $ minimum consistency, and $1 = $ maximum consistency.	onsistency).
286	5 The resultant vector angle Φ , ranging from -180° to -	+180°, is related to the average
287	7 relative phase between the onsets of the dyad, and was taken	as measure for a dyad's
288	3 synchronization <i>asynchrony</i> . For the analysis, two versions of	of this measure were considered,
289	namely a signed Φ (-180° to +180°) and an absolute Φ (0° to	(180°) . The signed Φ allowed to
290	0 assess leader-follower relationships (anticipation and delay)	in dyads in function of the
291	experimental conditions, while the absolute Φ provided a glo	bal measure of synchronization
292	2 <i>accuracy</i> , independent of leader-follower relationships.	

Timing (coefficient of variation (CV%) of inter-onset intervals). We calculated the coefficient of variation – as the standard deviation of a participant's IOIs across a trial divided by the mean IOI multiplied by 100 - to obtain a tempo-independent measure of the stability/variability of the performed inter-onset intervals (0 = no variability, to higher positive values = increased variability). As no significant differences were found between the CVs of a dyad within trials (p > .05), we took the average CV per trial as measure.

302 Analysis

Two general types of conditions can be distinguished in the experiment; a first type 303 304 pertains to conditions where the members of a dyad applied the same Movement type 305 (baseline, expressive gesture, or no movement), a second type to conditions where they applied a different Movement type (P1[expressive gesture]-P2[no movement], and P1[no movement]-306 307 P2[expressive gesture]). The data set was split accordingly, and different analyses were performed 308 on the two resulting data subsets (for a detailed description of the different features, see 309 section Dependent variables). For the *same* Movement type subset, the focus was on the 310 synchronization features consistency R and absolute asynchrony Φ , and on the timing feature 311 CV. For each of these features, a $3 \times 2 \times 2$ repeated measures ANOVA was applied with 312 Movement type (baseline/expressive gesture/no movement), Visual contact (yes/no), and 313 Tempo (fast/slow) as within-subjects factors. For the *different* Movement type subset, the 314 focus was on leader-follower relationships, which were quantified in the synchronization feature relative asynchrony Φ . For this feature, a 2×2×2 repeated measures ANOVA was 315 applied with Movement type (P1[expressive gesture]-P2[no movement]/ P1[no movement]-P2[expressive 316 gesture)), Visual contact (yes/no), and Tempo (fast/slow) as within-subjects factors. For each 317 subject, we calculated the average value of each dependent variable across the three trials 318 they performed in each condition. These values were then used to perform the respective 319 repeated measures ANOVAs. 320 321 For all tests, a significance level of .05 was applied. For the repeated measures 322 ANOVAs, Mauchly's tests of sphericity were used to check the assumption of sphericity. In 323 the case of non-sphericity, effects were Greenhouse-Geisser corrected. Post hoc tests to follow up on main and interaction effects were conducted as *t*-tests, with significance levels 324

- 325 corrected for multiple comparisons using the Bonferroni method.
- 326

327	Results
328	
329	Same Movement type
330	
331	Interpersonal synchronization: Absolute asynchrony Φ (Figure 3). The 3×2×2
332	repeated measures ANOVA revealed a main effect of Movement type, $F(1.098,12)=6.083$,
333	p < .05, and Visual contact, $F(1,12) = 8.38$, $p < .05$, while no interaction effects were observed.
334	Post hoc pairwise comparisons showed that the no movement Movement type (M=11.12,
335	SE=1.46) led to significantly higher absolute asynchronies compared to the baseline
336	Movement type (M=6.69, SE=0.80), $t(11)=3.43$, $p<.05$, $g=0.32$, and to the expressive gesture
337	Movement type (M=5.76, SE=0.73), $t(11)=3.85$, $p<.05$, $g=0.39$. In addition, we found that
338	the absolute asynchrony was significantly higher when people could not see each other
339	(M=9.28, SE=1.53) compared to when they could see each other (M=6.43, SE=1.04), $t(11) =$
340	2.90, <i>p</i> <.05, <i>g</i> =0.18.



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Figure 3. Mean absolute asynchrony Φ (in degrees) by: (left) Visual contact (yes/no) and (right) Movement type (baseline/expressive gesture/no movement). Error bars represent the standard error of the mean (* p<.05).

347	Interpersonal synchronization: Consistency R (Figure 4). The 3×2×2 repeated
348	measures ANOVA yielded a main effect of Movement type, $F(1.04,12)=8.65$, $p<.05$, Visual
349	contact, <i>F</i> (1,11) = 7.98, <i>p</i> <.05, and Tempo, <i>F</i> (1,12) = 125.55, <i>p</i> <.001. Also, we found a

significant interaction between Movement type and Tempo, F(1.487,12)=5.583, p<.05. Post hoc tests indicated a general decrease in synchronization consistency when no movements could be performed, and at the slower tempo. Interestingly, post hoc tests indicated an increase in synchronization consistency when expressive gestures are applied (M=0.9626, SE=0.0023) compared to the baseline Movement type condition (M=0.9554, SE=0.0033), but only for the slow Tempo, t(11)=3.72, p<.05, g=0.36.

Although no significant interaction effect was found between Movement type and Visual contact (F(1.227,12)=2.571, p=0.125), a similar pattern can be found; post hoc

358 pairwise comparisons revealed an increase in synchronization consistency when expressive

gestures are applied (M=0.9734, SE=0.0013) compared to the baseline Movement type

360 condition (M=0.9633, SE=0.0030), but only when there is visual contact, t(11)=3.72, p<.05,



³⁶¹ *g*=0.36.

Figure 4. Mean synchronization consistency R by: (left) Movement type (baseline/expressive gesture/no movement) and Tempo (slow/fast), and (right) Movement type
(baseline/expressive gesture/no movement) and Visual contact (yes/no). Error bars represent the standard error of the mean. Only significant posthoc results that are responsible for the

interaction effects are indicated by asterisks (* p<.05 and *** p<.001).

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Timing: Coefficient of variation (CV%) (Figure 5). The $3 \times 2 \times 2$ repeated measures ANOVA yielded a significant main effect of Movement type, F(1.612,12)=15.662, p<.001,

³⁶²

- and a significant interaction effect between Movement type and Visual contact,
- 372 F(1.89,12)=8.60, p<.05. In general, it was found that the CV% was higher with the no
- 373 movement Movement type, compared to the baseline Movement type, and the expressive
- 374 gesture Movement type. Concerning the interaction effect between Movement type and
- 375 Visual contact, post hoc tests indicated that it was driven by the finding that the expressive
- 376 movement Movement type (M=3.987, SE=0.158) lowered the CV compared to the baseline
- 377 Movement type (M=4.737, SE=0.205), but only when there was visual contact, t(11)=6.37,
- **378** *p*<.001, *g*=0.53.
- 379



380	Figure 5. Mean coefficient of variation of the IOIs (CV%) by Movement type
381	(baseline/expressive gesture/no movement) and Visual contact (yes/no). Error bars represent
382	the standard error of the mean. Only significant posthoc results that are responsible for the
383	interaction effects are indicated by asterisks (*** p<.001).
384	
385	Different Movement type
386	
387	Leader-follower relationship: Signed asynchrony Φ (Figure 6). The 2×2×2
388	repeated measures ANOVA revealed a main effect of Movement type combination,
389	F(1,12)=29.47, $p<.001$, as well as significant interaction effects between Movement type and
390	Tempo, $F(1,12)=8.31$, $p<.05$, Movement type and Visual contact, $F(1,12)=7.22$, $p<.05$, and
391	between Movement type, Tempo and Visual contact, $F(1,12)=10.13$, $p<0.01$. The main effect
392	of Movement type indicated that within dyads, participants that performed the expressive
393	gesture Movement type were, on average, ahead of (cf. leading) participants that performed
394	the no movement Movement type. Additional post hoc tests that were conducted to better

- 395 understand the three-way interaction pointed out that this effect was more pronounced at the
- slow Tempo and when Visual contact was allowed (M=-10.41, SE=3.18 versus M=10.13,
- 397 SE=2.99, t(11), p<.001, g=0.55) compared to the other conditions (slow Tempo/no Visual
- 398 contact, fast Tempo/Visual contact, and fast Tempo/Visual contact), where effects were
- 399 significant only at the .05 level.
- 400



Figure 6. Mean signed asynchrony Φ (in degrees) by Movement type combination (P1_[expressive gesture]–P2_[no movement]/P1_[no movement]–P2_[expressive gesture]), Tempo (slow/fast), and Visual contact (yes/no). A negative Φ means that P1 is ahead of P2 while, reversely, a positive Φ means that P1 is lagging behind P2. Error bars represent the standard error of the mean. Only significant posthoc results that are responsible for the interaction effects are indicated by asterisks (* p<.05 and *** p<.001).

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Discussion

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In this study, the primary aim was to investigate the role of body movements in 411 412 musical communication, in terms of interpersonal synchronization, timing control, and 413 leader-follower relationships. We experimentally controlled for the use of hand and arm 414 movements in a musical task, in which dyads were asked to synchronously tap out a melody. Next to their comfortable/natural way of tapping, we instructed participants to either perform 415 416 pronounced expressive hand and arm gestures in between successive taps, or to restrict from 417 any overt body movement. In general, our results show that these different movement types 418 can indeed influence the musical communication process. In addition to the study of

419 movement type, we investigated the role of tempo and visual contact in the communication420 process.

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422 Compared to when musicians tap in a spontaneous natural way, we found that a 423 restriction of body movements resulted in a general lower accuracy (= higher absolute 424 asynchrony Φ) and consistency (= smaller R) of interpersonal synchronization, and in a 425 significant increase of the variability of produced inter-onset interval durations. Effects 426 related to the use of expressive gestures were more nuanced, as they were modulated by the 427 factors tempo and/or visual contact. A first finding was that tapping using expressive hand 428 and arm gestures did not change synchronization accuracy (= asynchrony) with respect to 429 natural tapping. However, we found that interpersonal synchronization was in general more 430 consistent (that is, tone onsets had a more consistent phase relationship) when dyads 431 performed expressive gestures in between tapping onsets, but only when there was an 432 exchange of visual information, and at slower tempi. A related observation was made for the 433 variability/stability of produced inter-onset interval durations. Again, it was found that 434 tapping using expressive gestures could improve stability of performed inter-onset interval 435 durations, but only under the condition of an exchange of visual information.

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437 These results suggest that the use of expressive gestures of musicians may have 438 beneficial effects on interpersonal coordination, but that it requires sufficient time to actually 439 execute the gestures, and that there is an exchange of visual information. The explanation of 440 this finding is supposedly linked to the time-varying perceptual properties of both the 441 external visual input of the partner's body movements, and of the internal somatosensory and 442 proprioceptive feedback of one's own movements. Previous research has indicated that 443 humans are highly receptive to these time-varying sensorimotor properties for (emergent) 444 time-keeping purposes (Coull & Droit-Volet, 2018; Maes, Giacofci, et al., 2015; Motanis et 445 al., 2018; Schwartze et al., 2012). This may allow humans to accurately anticipate the 446 occurrence of specific sensory events, and hence support interpersonal synchronization and 447 timing. A critical question though is about the principles and mechanisms underlying this 448 anticipatory behavior. Currently, a central debate in cognitive (neuro)science and cybernetics revolves around the concepts of 'weak anticipation' and 'strong anticipation' (Dubois, 2003; 449 Stepp & Turvey, 2010), referring respectively to a computational/inferential and behavioral 450 dynamics/ecological approach to human motor control (Gallagher & Allen, 2018; Nasuto & 451 452 Hayashi, 2016, 2019; Warren, 2006). Weak anticipatory behavior involves the construction

453 of predictions of the environment's future states based on internal models of the environment 454 (cf. forward models). Based on predictions and error-correction mechanisms, agents can plan 455 their motor actions and adapt flexibly to changing environmental conditions. According to 456 this model-based approach, the connection between the agent and its environment is not direct, but mediated by a mental model. Alternatively, strong anticipatory behavior is 457 458 fundamentally rooted in the direct (action-perception) coupling of an agent with its 459 environment, forming a dynamical system that is driven towards stable relationships between its components (as for example described by the relative phase in periodic behaviors). In this 460 461 regard, anticipatory behavior in joint motor coordination may be the outcome of a moment-462 to-moment alignment of actions to perceptual information (Kelso, 1995; Wilson & Golonka, 463 2013), of the introduction of small time-delayed self-feedback (Demos, Layeghi, Wanderley, 464 & Palmer, 2019; Roman, Washburn, Large, Chafe, & Fujioka, 2019; Stepp & Turvey, 2010; Washburn, Kallen, Coey, Shockley, & Richardson, 2015), or of long-term complexity 465 466 matching of joint behavior (Fine, Likens, Amazeen, & Amazeen, 2015; Marmelat & Delignières, 2012). These studies provide valuable mathematical methods for the analysis 467 468 and modeling of complexity and fluctuation structures in joint behavior, with a central focus on nonlinear, time-varying characteristics of this behavior. These methods typically rely on 469 470 fairly large amounts of data, which were not available in the present study. However, our 471 experimental paradigm, as well as similar paradigms in the domain of music interaction, are 472 valuable as they provide excellent scenarios for studying the mechanisms of weak and strong anticipation. For that purpose, scenarios of music interaction lend themselves ideally in the 473 474 way they allow to control, manipulate, and perturb variables that relate with personal 475 background, sensory coupling, musical properties such as tempo, and so forth. The 476 combination of versatile musical environments, and nonlinear time-series analysis methods holds great value in the further study of embodied human interaction and its underlying 477 478 control mechanisms. 479 The main contribution of our study pertains to the role of body movement – in 480 particular of expressive, ancillary gestures (Cadoz & Wanderley, 2000) – in musical 481 482 communication. Earlier research demonstrated that visual information of performers' gestures may influence listener's perception of musical parameters (Schutz & Lipscomb, 2007; 483 Thompson et al., 2010), as well as of musical emotion and expressiveness (Dahl & Friberg, 484 2007; Davidson, 1993, 2012; Krahé et al., 2015; Thompson et al., 2005; Vines et al., 2011; 485 Vuoskoski et al., 2014). Interestingly, research showed that performers' (ancillary) gestures 486

487 may equally support the communication of musical intentions to co-performers, both on the expressive-emotional and music-structural level. In particular, in cases where auditory 488 information is absent or not reliable, performers may rely on visual cues to support musical 489 timing (Bishop & Goebl, 2015; Demos et al., 2017; Goebl & Palmer, 2009). The current 490 491 study supports this line of research by showing improved joint timing when expressive 492 gestures are allowed. In addition to the exchange of visual information, beneficial effects on 493 timing have also been related to the execution itself of ancillary gestures. In studies on regular interval timing, a distinction is typically made between two possible timing 494 495 mechanisms, namely an event-based timing mechanism, when discrete movements are 496 produced, and an emergent timing mechanism, when smooth continuous movements are produced (Delignières et al., 2004; Robertson et al., 1999; Torre & Balasubramaniam, 2009). 497 498 In the former, timing is regulated by internal timekeeping mechanisms employing cognitive 499 resources, while in the latter, time and timekeeping are emergent (inherent) properties of the 500 movement and the related feedback itself. Research has shown that emergent timing may be 501 more robust in highly cognitive demanding situations, such as music performance, as 502 timekeeping is "outsourced" to the motor system (Maes, Giacofci, et al., 2015; Maes, Wanderley, et al., 2015). Also in this regard, the use of ancillary gestures may provide a 503 504 compensatory strategy to optimize joint timing in music performance. To distinguish between 505 the effects of visual exchange of gestural information and movement execution itself, we 506 controlled for visual contact between musicians. The fact that the use of natural/comfortable 507 and expressive gestures without visual contact led to a more consistent interpersonal timing 508 and a lower IOI variability, compared to when no movement was allowed, suggests that 509 movement execution itself – and underlying emerging timing mechanisms – positively 510 influence interpersonal timing. Although there was no difference between the use of 511 natural/comfortable gestures and expressive gestures when visual contact was absent, we did found a higher consistency and lower variability for expressive gestures when visual contact 512 513 was allowed. This finding indicates that the exchange of visual information inherent to 514 expressive gestures may have an additional beneficial effect on interpersonal timing, on top of the effect of movement execution itself. It must be noted that our experiment focused on 515 516 musicians (> six years of formal music training). It would be of interest to investigate further whether these results are generalizable to broader populations of non-musicians. We would 517 expect that effects in musicians are more pronounced as musicians have presumably 518 developed specific strategies for using multimodal information about their own and/or other's 519

520 gestures for timing control through musical practice and experience.

An important additional aim of the current study was to investigate leader-follower 522 523 relationships in musical dyads and the way these depend on the produced movement types. In 524 previous research, it had been shown that assigned leader-follower roles are reflected in musicians' body movements and their coordination (Goebl & Palmer, 2009; Keller & Appel, 525 526 2010). For instance, Keller and Appel (2010) demonstrated that sound synchrony of duetting 527 pianists increased when the body sway of the leader (primo player) preceded the body sway of the follower (secondo player). In line with this finding, Goebl and Palmer (2009) had 528 529 found that head movements of pianists that were assigned the leader role preceded those of 530 the follower. Interestingly, it was also found that leader pianists raised fingers higher than the 531 follower pianists. Typical for these studies was that leader-follower roles are assigned 532 beforehand, and bodily coordination was studied as a result. In the current study, this 533 paradigm was reversed as we assigned specific body movements to our participants 534 beforehand (baseline, no movement, expressive gesture), and studied the effect on the leaderfollower relationship within the dyads. An important finding of the study was that assigned 535 536 body movements indeed had an effect. In general, the produced onsets of musicians that were asked to perform expressive gestures in between onsets were preceding their partner who 537 538 could not produce any movement in between produced onsets. This supports the idea that 539 musicians who produce expressive gestures are inclined to take the leader role and vice versa. 540 Similar to the interpersonal timing measures consistency and variability, this effect was 541 modulated by the factors visual contact and tempo. It was shown that the effect was most 542 pronounced when musicians' could see each other, and when they had enough time to 543 effectively produce expressive gestures (slow tempo). Again, this could be explained by the presence of temporal cues in the expressive gestures. By allowing performers to gesture 544 expressively, they are empowered to communicate temporal information, and hence, to 545 546 function as a temporal reference for interpersonal coordination. These results are in line with other research studying the role of gestural communication in leader-follower dynamics. For 547 instance, Gerpott and colleagues (2018) found that emergent leaders (in initially leaderless 548 groups) exhibit more active body language (in particular of arms and shoulders) and less 549 550 passive facial expressions. Also, Talley and Temple (2015) point towards the role of the type 551 of hand gesture of leaders in establishing a certain relationship quality (i.e., positive hand gestures create immediacy and attraction between leaders and followers). The results of the 552 present study contribute to this line of research within the domain of music interaction. They 553 554 are promising and would benefit from follow-up studies that investigate into more detail the

555	relationship between bodily gestures and leader-follower roles, and the influence thereon of
556	person-, context-, and task-related factors and constraints. Particularly interesting would be to
557	investigate this relationship in "real-life" musical contexts, such as in (jazz) ensemble
558	improvisations, which are often characterized by a rhythm section (bass, drums) that supports
559	a more expressive lead soloist, but where there is equally room for shifting roles through solo
560	improvisations of any instrument.
561	
562	Conclusion
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564	The present study investigated the role of body movement (natural movement/no
565	movement/expressive movement), visual contact (yes/no) and tempo (slow/fast) in joint
566	musical performances (duet, melody tapping task), in terms of timing control,
567	synchronization and leader-follower dynamics. The results show that the restriction of body
568	movements has detrimental effects on interpersonal timing and synchronization (lower
569	synchronization accuracy and consistency, and higher inter-onset variability). In contrast, the
570	use of expressive gestures led to a higher synchronization consistency, compared to natural
571	gestures, but only when there was visual contact and at the slower tempo. The same finding
572	was observed for the inter-onset variability. Finally, results indicated that the type of body
573	movements performed by the members of a dyad can modulate leader-follower dynamics. In
574	general, it was found that people that performed expressive body movements tended to take
575	the leader role in the interaction. These results suggest that expressive body movements
576	contain time-varying cues (internal and external), that facilitate anticipation mechanisms and,
577	in turn, may improve interpersonal timing.
578	
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583	experiments.
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587	References
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